

TOSHIBA MACHINE'S SCARA Robots TH Series

TH1050A

- **HIGH LOAD CAPACITY** ·· Maximum 20kg
- **HIGH SPEED** ·· Cycle time 0.39s
(With 2kg payload)
- **POSITIONING REPEATABILITY**
· X, Y ±0.01mm, Z ±0.01mm, C ±0.004 deg
- **HIGH RIGIDITY**
- **BUILT-IN PLC** ·· Ready for Touch-Sensitive
Operation panel
- **DUCT-LESS DESIGN**

Robot specifications



Model	TH1050A
Type	Horizontal Multi-joint
Number of controlled axis	4
Arm length	1050mm (550mm+500mm)
Working envelope	Axis 1: ±160° Axis 2: ±145° Axis 3(Z-axis): 200mm (Option: 400mm) Axis 4(Z-axis rotation): ±360°
Maximum speed	Axis 1: 300°/s Axis 2: 420°/s Axis 3(Z-axis): 2050mm/s Axis 4(Z-axis rotation): 1200°/s Composite: 9.15m/s
Standard cycle time (with 2kg payload)*1	0.39s
Maximum payload mass**2	20kg
Allowable moment of inertia at end***2	0.2kgm²
Positioning repeatability*3	X-Y(Plane): ±0.01mm Z-axis (vertical): ±0.01mm Axis 4(Z-axis rotation): ±0.004°
Input/output signals for hand	5 inputs / 4 outputs
Air piping for hand	φ6 x 4 pcs.
Position detecting system	Absolute system
Robot-controller cable	5m (Optional length maximum 25m)
Mass	80kg

*1: Continuous operation of standard cycle motion pattern is not possible beyond the effective load ratio.
(Horizontal 300mm, vertical 25mm, round-trip, coarse positioning)

*2: Maximum speed rates and acceleration rates are limited depending on motion patterns, payload mass, and offset value.

*3: When the environment temperature is constant.

Controller specifications



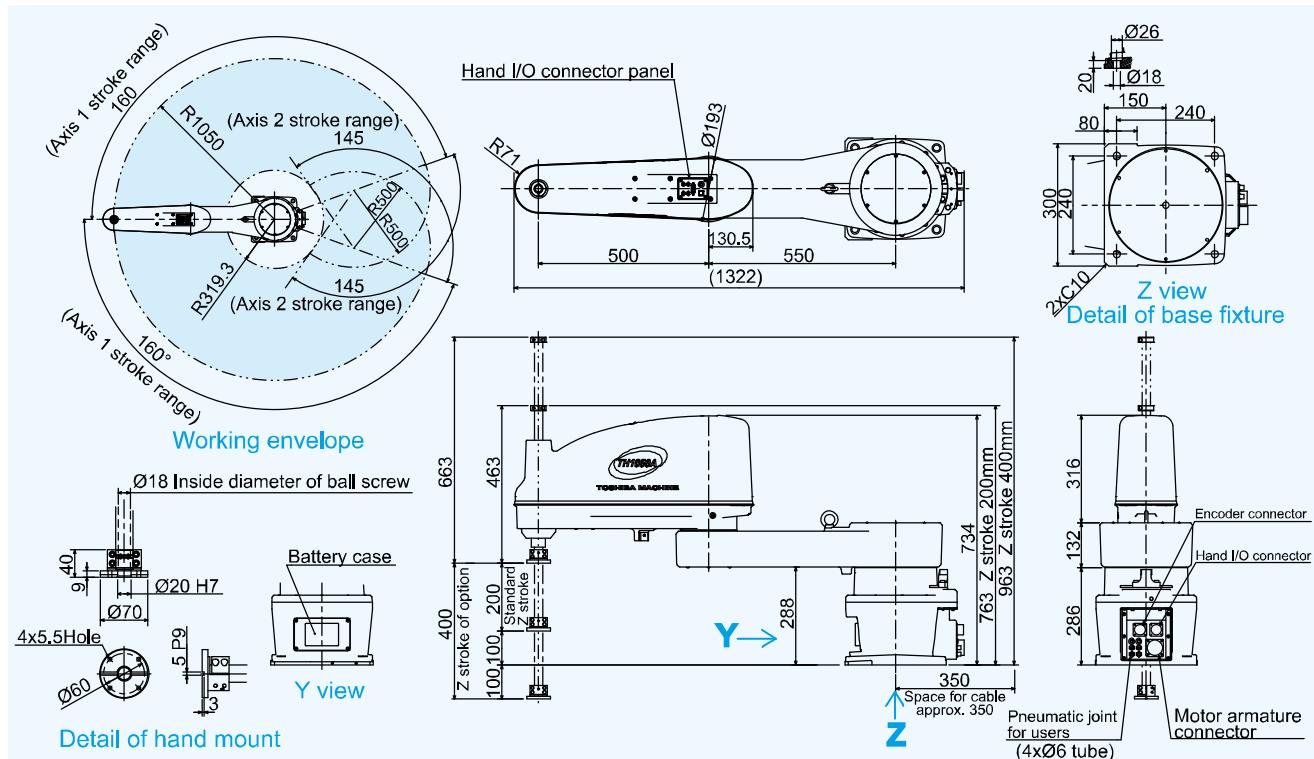
Controller
TS3100

Model	TS3100
No. of axis	No. of simultaneously controlled axes: 8 axes (2 additional axes under development)
Operation mode	PTP, CP (linear, Circular), Short-cut, Arch motion
Storage capacity	Total: 12800 points + 25600 steps 1 program: 2000 points + 3000 steps
No. of programs	Max, 256 (247 user files + 9 system files)
Programming language	SCOL (proprietary, similar to BASIC)
Teaching unit (option)	Teach pendant TP1000, with 5-meter cable (Program can be written on PC)
External I/O	32 inputs/32 outputs
Hand control signals	8 inputs/8 outputs
External operation signal (exclusive)	Inputs: Program selection, start, stop, reset, etc Outputs: Servo-On status, emergency stop, ready for operation, malfunction alarm, etc
Serial communication port	RS-232C: 2 ports, Ethernet: 1 port*4
Other functions	Torque control, Interruptive functions, self-diagnosis, I/O control and communications during motion, Coordinate calculations, Built-in PLC, etc
Power supply	Single phase AC200V~240V 50/60Hz 4.4kVA
Outer dimensions and mass	420W×230H×298D (mm), 17kg
PC software (option)	TSPC: Program editor, Teaching, Remote operation, etc
Options	I/O extension, I/O cables, Field Network (CC-Link, DeviceNet, Profibus)*4
External Memory	USB memory

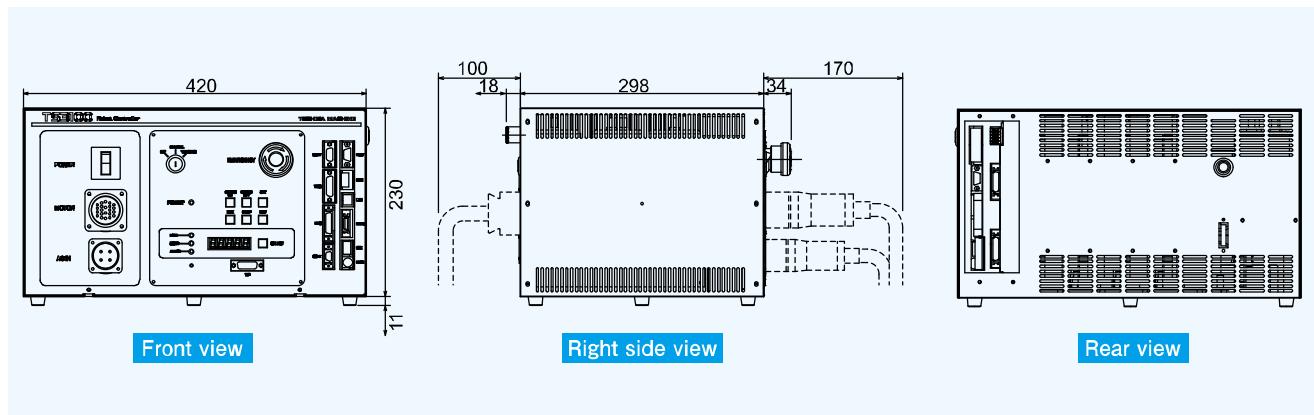
*4: Ethernet is a registered trademark of XEROX Corp. in the U.S.A.
CC-Link is a registered trademark of CC-Link Partner Association.
DeviceNet is a registered trademark of ODVA.
Profibus is a registered trademark of Profibus User Organization.

TEACH PENDANT(OPTION)

■ TH1050A External view



■ TS3100 External view



TOSHIBA MACHINE CO.,LTD. HEAD OFFICE
Control Systems Sales Department, Control Systems Division
2068-3, Ooka, Numazu-shi, Shizuoka-ken 410-8510, Japan
TEL:[81](0)55-926-5032 FAX:[81](0)55-925-6527

TOSHIBA MACHINE CO.,AMERICA.
755 Greenleaf Avenue, EIK Grove Village, IL 60007, U.S.A.
TEL:[1]847-593-1616 FAX:[1]847-593-0897

TM ROBOTICS (EUROPE) LTD.
Unit 2, Bridge Gate Center, Martinfield,
Welwyn Garden City, Herts, AL7 1JG,UK
TEL [44](0)1707-290370 FAX [44](0)1707-376662

URL:http://www.toshiba-machine.co.jp/english/product/sr_e/index.html
<http://www.toshiba-machine.com>
<http://www.tmrobotics.co.uk>



Before operating the industrial robot, read through
and completely understand the instruction manuals.

■ The contents included in this catalog are subject to
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